

3. Find the weights w_1, w_2 and sample points r_1, r_2 for the Gauss 2 point quadrature rule $\int_0^h f(x) dx \approx w_1 h f(r_1 h) + w_2 h f(r_2 h)$. (Hint: You should make some simplifying assumptions first, based on symmetry)

4. Consider the multi-step method:

$$U(t_{k+1}) = -4U(t_k) + 5U(t_{k-1}) + 4hf(t_k, U(t_k)) + 2hf(t_{k-1}, U(t_{k-1}))$$

- a. Calculate the truncation error. Is the method consistent?

- b. Determine if the method is stable.

- c. Is the method implicit or explicit?

5. If $L_N(x)$ is the Lagrange polynomial of degree N which interpolates to $f(x) = e^{2x}$ at $x = 1, 2, 3, \dots, N+1$, prove that $L_N(0)$ does NOT converge to $f(0) = 1$, as $N \rightarrow \infty$.
6. A 3 by 3 matrix A has eigenvalues very near 2, 8 and 9. If the shifted power method (note: not INVERSE shifted power method) $x_{n+1} = (A - pI)x_n$ is used, what value of p should be used if we want to maximize the speed of convergence to find the eigenvalue near 9? (Hint: the rate of convergence of the power method is the ratio of the second largest (in absolute value) eigenvalue to the largest.)

7. The following MATLAB program solves a linear system $Ax = b$ using the Gauss-Jordan algorithm, in which A is reduced to diagonal form rather than upper triangular form, during the forward elimination (no pivoting is done in this program). For large N , approximately how many multiplications are done by this program? How does this algorithm compare in speed to normal Gauss elimination?

```
function x = GJ(A,b,N)
for i=1:N
    for j=1:N
        if (j==i)
            continue
        end
        r = A(j,i)/A(i,i);
        for k=i:N
            A(j,k) = A(j,k) - r*A(i,k);
        end
        b(j) = b(j) - r*b(i);
    end
end
for i=1:N
    x(i) = b(i)/A(i,i);
end
```