

Math 5330, Test I

Name _____

1. a. Show that any matrix which has a "Cholesky" decomposition $A = LL^T$, with L nonsingular, is positive definite, that is, show it is symmetric and $x^T Ax > 0$ for any nonzero vector x .

- b. Show that

$$A = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 2 & 1 & 0 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

is positive definite, by finding its LU decomposition.

2. An N by N band matrix has $N^{1/3}$ non-zero diagonals below the main diagonal and the same number above. If N is large, approximately how many multiplications are done:
- during the forward elimination, if no pivoting is done?
 - during the forward elimination, if partial pivoting is done?
 - during back substitution, if no pivoting is done?
 - during back substitution, if partial pivoting is done?

3. A MATLAB program which solves a symmetric linear system, with no pivoting, does most of its work in the loops:

```
for I=1:N-1
    for J=I+1:N
        for K=J:N
            A(J,K) = A(J,K) - LJI*A(I,K)
        end
    end
end
```

Approximately how many multiplications are done (show work)? How does this compare to Gaussian elimination for a nonsymmetric system?

4. a. If a matrix is decomposed into its (strictly) subdiagonal, diagonal, and (strictly) superdiagonal parts, $A = L + D + U$, the Jacobi iterative method for solving $Ax = b$ will converge if and only if all eigenvalues of what matrix are less than 1 in absolute value?
- b. Same question, for the Gauss-Seidel method.
- c. Using parts [a.] and [b.], show that both Jacobi and Gauss-Seidel methods will converge if A is either upper triangular or lower triangular, and all its diagonal elements are nonzero. (Hint: the eigenvalues of an upper or lower triangular matrix are its diagonal entries.)

5. Approximately how many significant digits would you expect in the solution of $Ax = b$ if Gaussian elimination with partial pivoting is used on a computer with machine precision $\epsilon = 10^{-12}$, and

$$A = \begin{bmatrix} 1.000001 & 1 \\ & 1 & 1 \end{bmatrix}$$

6. Define:

- a. orthogonal matrix
- b. lower Hessenberg matrix
- c. permutation matrix
- d. $\|x\|_p$, if x is a vector and $1 \leq p < \infty$
- e. $\|A\|_p$, if A is a matrix