

1. Consider the method ( $U_i^k = U(x_i, t_k)$ )

$$\frac{U_i^{k+1} - U_i^k}{dt} = \frac{U_i^k - U_{i-1}^k}{dx}$$

- a. Calculate the truncation error, when this is used to approximate  $u_t = u_x$ . What can you say about the consistency of this method?

- b. Use the Fourier method to analyze stability, that is, plug in  $U_i^k = a_k e^{Imx_i}, I = \sqrt{-1}$ .

2. Explain why the fact that the exact solution at  $(x, t), t > 0$  of the heat equation  $u_t = Du_{xx}, u(x, 0) = h(x)$  depends on the initial conditions at all points  $x$ , shows that the usual explicit finite difference method cannot possibly be stable if  $dt$  and  $dx$  go to 0 with any constant ratio  $dt/dx = r$ .

3. Analyze the stability of the following approximation to  $u_{tt} = c^2 u_{xx}$  :

$$\frac{U_i^{k+1} - 2U_i^k + U_i^{k-1}}{dt^2} = c^2 \frac{U_{i+1}^{k+1} - 2U_i^{k+1} + U_{i-1}^{k+1}}{dx^2}$$

Hint:  $e^\theta - 2 + e^{-\theta} = -4\sin^2(\theta/2)$

4. a. Calculate the truncation error for the following approximation to  $u_{xxxx} = 1$ , where  $U_i = U(x_i)$ .

$$\frac{U_{i+2} - 4U_{i+1} + 6U_i - 4U_{i-1} + U_{i-2}}{dx^4} = 1$$

b. Assume the boundary conditions for (a) are  $u(0) = u_{xx}(0) = u(\pi) = u_{xx}(\pi) = 0$ . Then (a) is a system of linear equations of the form  $Au = f$ . Given that the eigenvectors of the matrix  $A$  are  $W_i = \sin(mx_i)$ , for integer  $m$ , find the eigenvalues. Hint:  $\sin(m(x+dx)) + \sin(m(x-dx)) = 2\sin(mx)\cos(m dx)$  and  $\cos(2\theta) = 2\cos^2(\theta) - 1$ .

c. Write out the Gauss-Seidel iteration to solve the finite difference equations of (a).

d. Is the Gauss-Seidel iteration of part (c) guaranteed to converge? Justify your answer.

5. True or False:

- a. Choosing the shift parameter closer to an eigenvalue will generally make the shifted inverse power method converge more rapidly to this eigenvalue.
- b. If SOR is applied to solve the equations of Problem 4a, it is guaranteed to converge for  $0 < \omega < 2$ .
- c. It is possible to apply the shifted inverse power method to the generalized eigenvalue problem  $Az = \lambda Bz$ , where  $A$  and  $B$  are banded matrices, without having to deal with full matrices.
- d. Successive overrelaxation applied to  $Ax = b$ , with  $\omega = 1$ , is guaranteed to converge if the matrix  $A$  is diagonal dominant or positive definite or negative definite.
- e. For the transport equation  $u_t = -\nabla \cdot (u\mathbf{v})$ , the boundary conditions should be specified on the part of the boundary where  $\mathbf{v} \cdot \mathbf{n}$  is positive.
- f. The explicit upwind approximation to the transport equation is unconditionally stable.
- g. For the diffusion equation  $u_t = Du_{xx}$ , the speed of diffusion is infinite, while for the wave equation  $u_{tt} = c^2u_{xx}$  the velocity is finite.
- h. If the shifted inverse power method is used to find an eigenvalue of a matrix, with fixed shift, the  $LU$  decomposition found on the first iteration can be used on subsequent iterations to decrease the computer time for these iterations.
- i. If an implicit finite difference method is used to solve  $U_t = U_{xx} + U_{yy} + U_{zz}$ , you will need to solve a large linear system each time step which is banded, but sparse even inside the band.
- j. Nonlinear overrelaxation generally takes more work per iteration than Newton's method, but fewer iterations to converge.