### Max flow min cut in higher dimensions

#### Art Duval<sup>1</sup> Caroline Klivans<sup>2</sup> Jeremy Martin<sup>3</sup>

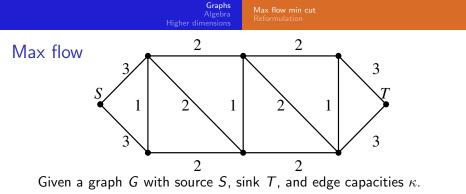
<sup>1</sup>University of Texas at El Paso

<sup>2</sup>Brown University

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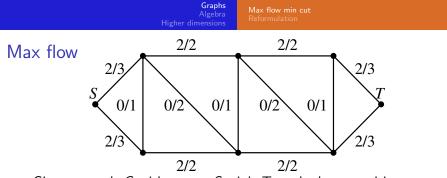
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Duval, Klivans, Martin Max flow min cut in higher dimensions

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Given a graph G with source S, sink T, and edge capacities  $\kappa$ .

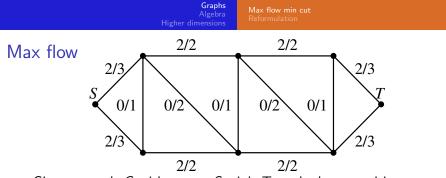
#### Definition

Flow on G is an assignment of flow  $x_e$  (non-negative number, and direction) to each edge such that:

▶ net flow at each vertex, except S and T, is zero; and

$$|x_e| \le \kappa_e.$$

Value of flow is outflow(S) = inflow(T).



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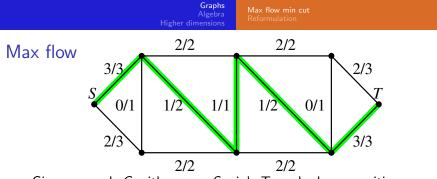
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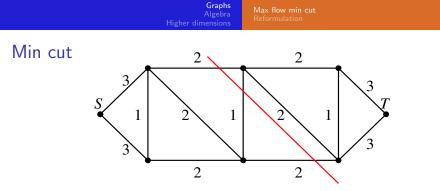
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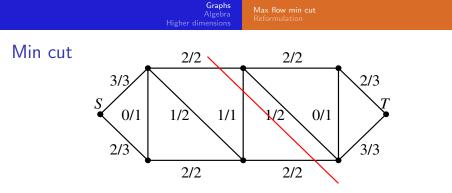
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#### Definition

Cut is minimal set of edges whose removal disconnects S from T. Value of cut is  $\sum_{e \in \text{cut}} \kappa_e$ .

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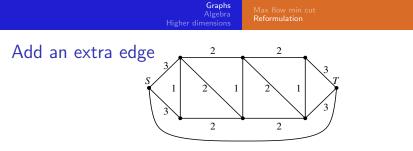
#### Definition

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Theorem (Classic max flow min cut)

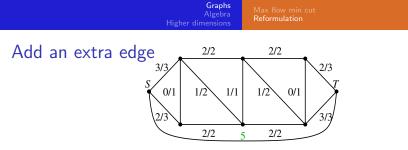
Max flow = min cut.

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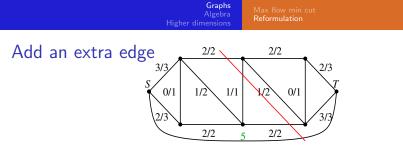
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#### Definition

Cut is minimal set of edges, including  $e_0$ , whose removal disconnects G. Value of cut is  $\sum_{e \in \text{cut} \setminus e_0} \kappa_e$ .

### Flows and boundary



Assign orientation to each edge (flow going "backwards" gets negative value)

$$\mathsf{netflow}(v) = \sum_{v=e^+} x_e - \sum_{v=e^-} x_e = \sum_{v\in e} (-1)^{\varepsilon(e,v)} x_e = (\partial x)_v$$

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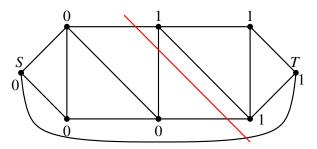
So net flow condition is  $\partial x = 0$ .

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Graphs Algebra Higher dimensions Boundary matrix Linear programming

### Cuts and coboundary

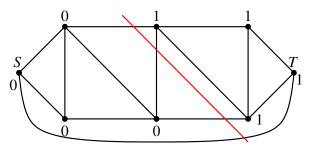
Assign 1 to every vertex in connected component with T, 0 to others. Let  $y_v$  be value at v. Edges in cut are those that have both 0 and 1 endpoints.



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## Cuts and coboundary

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Coboundary will do this:  $\partial^T y$  (linear combination of rows of  $\partial$ ) gives characteristic vector of cut.

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### Linear programming

Flow is now a linear program

- Find vector x (in edge space)
- $\partial x = 0$  (x is in flow space)
- $-\kappa_e \leq x_e \leq \kappa_e$  (can omit  $e_0$ )
- ▶ max *x*<sub>0</sub>

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The dual program is (can easily be reworked to say):

- Find vector y (in vertex space)
- Let  $u = \partial^T y$  (in cut space)
- ▶  $u_0 = 1$
- min  $\sum_e \kappa_e |u_e|$

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Linear programming says the solutions are equal; with some effort we can show the solution to the dual LP is the min cut problem.

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## Max flow in higher dimensions

Example: 2-dimensional complex;  $\partial$  maps 2-dimensional cells (polygons) to edges.

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## Max flow in higher dimensions

Example: 2-dimensional complex;  $\partial$  maps 2-dimensional cells (polygons) to edges.

- Find vector x (in polygon space)
- $\partial x = 0$  (x is in flow space)
- $-\kappa_p \leq x_p \leq \kappa_p$  (can omit  $p_0$ )
- identify designated polygon p<sub>0</sub>; max x<sub>0</sub>

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- identify designated polygon p<sub>0</sub>; max x<sub>0</sub>

Find a 1-dimensional cycle on the complex, and attach a polygon face filling that cycle. We are trying to maximize circulation on that designated polygon (around that cycle), while making all circulation balance on each edge.



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Linear programming says the solutions are equal; with some effort we can show the solution to the dual LP is the min cut problem. In particular, the support on this cut is a minimal set of polygons whose removal introduces codimension-1 homology, e.g., 1-dimensional "circular" hole in 2-dimensional complex

# Summary

### Theorem (DKM)

The max circulation around a codimension-1 cycle (e.g., 1-dimensional cycle in 2-dimensional complex) equals the value of a minimum cut containing the added face that fills in the cycle (e.g., polygon filling in 1-dimensional cycle).

Fine print:

- cut is minimal set of faces whose removal increases codimension-1 homology
- cut vector is in span of row space of boundary matrix
- normalize cut vector by specifying its value is 1 on p<sub>0</sub>, the added filling-in face
- cut vector might not be all 1's and 0's
- value of cut is inner product of capacities with cut vector

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